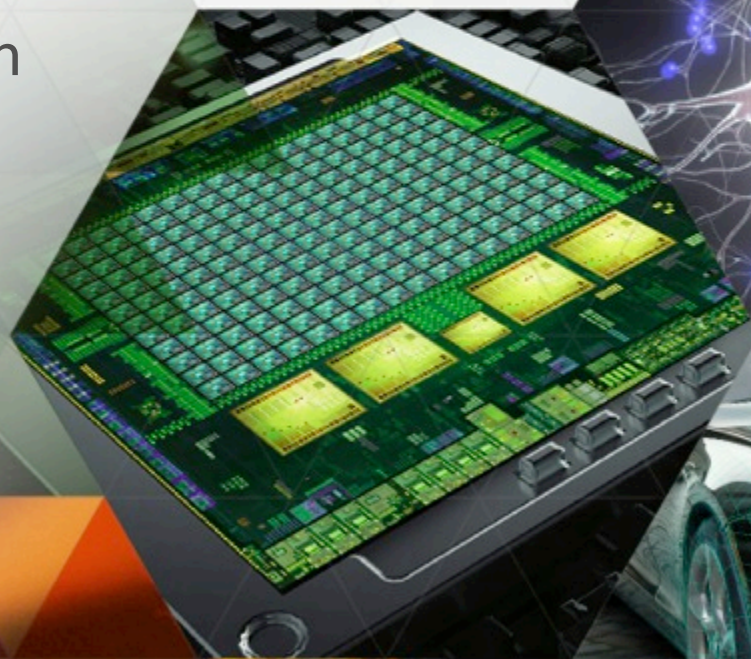




DEEP LEARNING WITH GPUS

Maxim Milakov, Senior HPC DevTech
Engineer, NVIDIA



**TOPICS
COVERED**

Convolutional Networks
Deep Learning
Use Cases
GPUs
cuDNN

MACHINE LEARNING

- ▶ Training

- ▶ Train the model from supervised data

- ▶ Classification (inference)

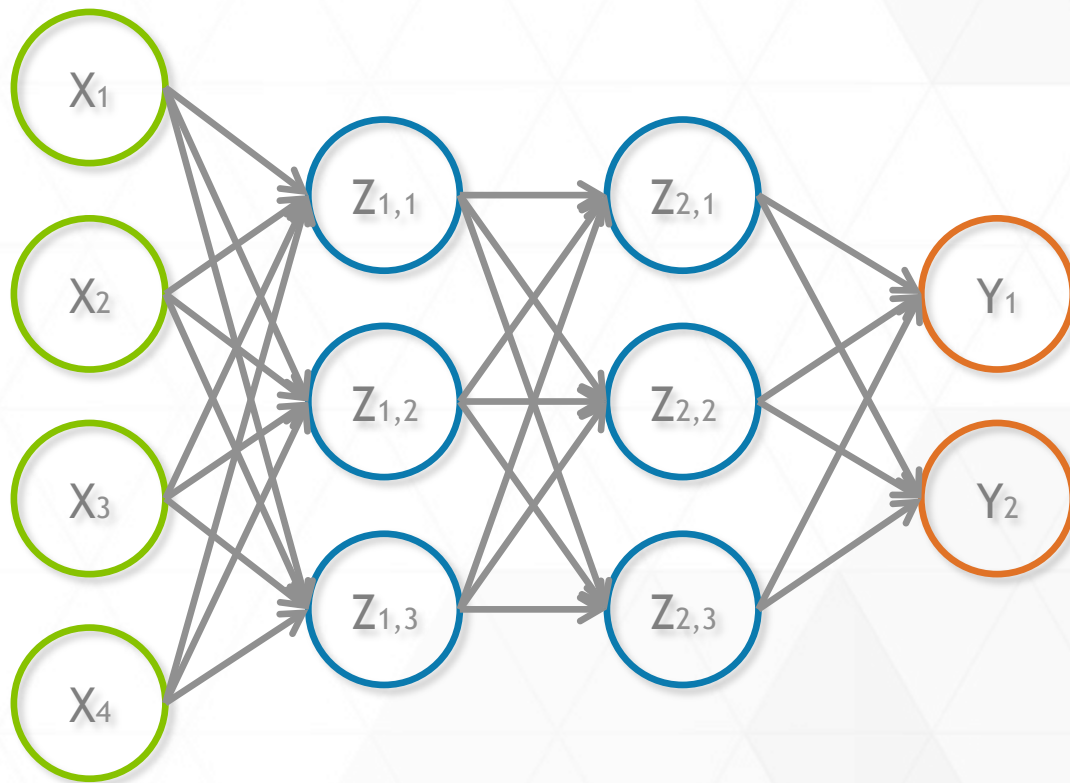
- ▶ Run the new sample through the model to predict its class/function value



ARTIFICIAL NEURAL NETWORKS

Deep networks

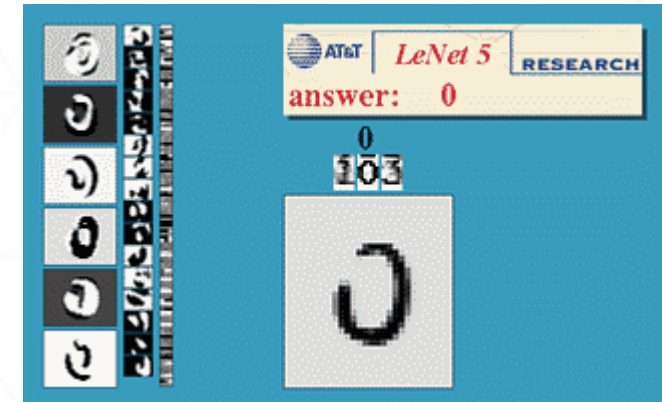
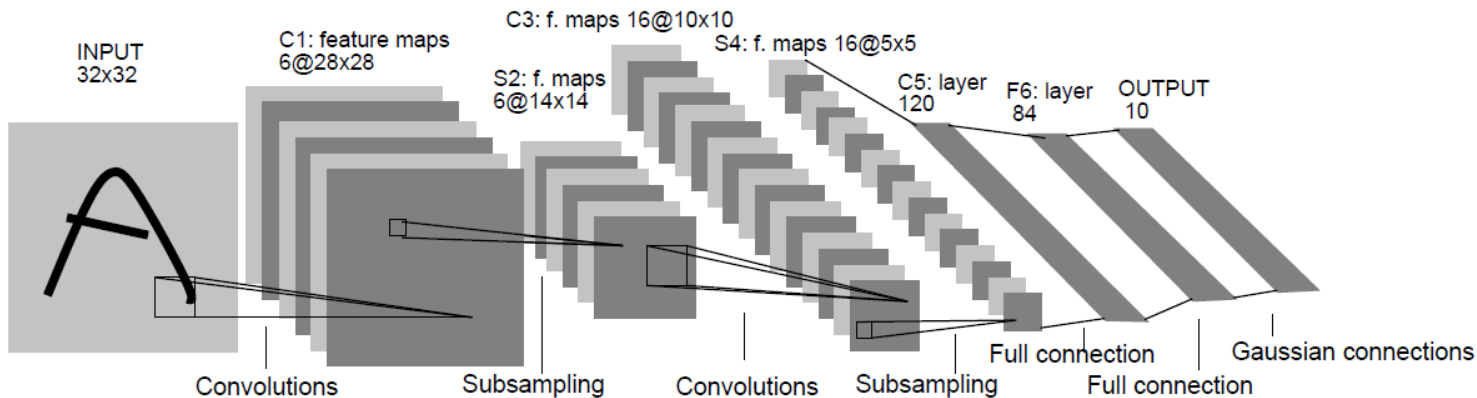
- ▶ Deep nets: with multiple hidden layers
- ▶ Trained usually with backpropagation



CONVOLUTIONAL NETWORKS

Local receptive field + weight sharing

- ▶ Yann LeCun et al, 1998



- ▶ MNIST: 0.7% error rate

*High need for computational resources
Low ConvNet adoption rate until ~2010*

TRAFFIC SIGN RECOGNITION

GTSRB

- ▶ The German Traffic Sign Recognition Benchmark, 2011

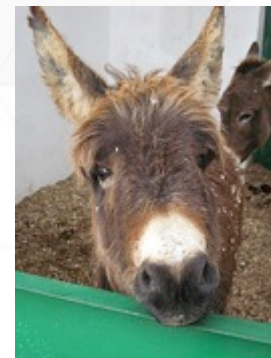


Rank	Team	Error rate	Model
1	IDSIA, Dan Ciresan	0.56%	CNNs, trained using GPUs
2	Human	1.16%	
3	NYU, Pierre Sermanet	1.69%	CNNs
4	CAOR, Fatin Zaklouta	3.86%	Random Forests

NATURAL IMAGE CLASSIFICATION

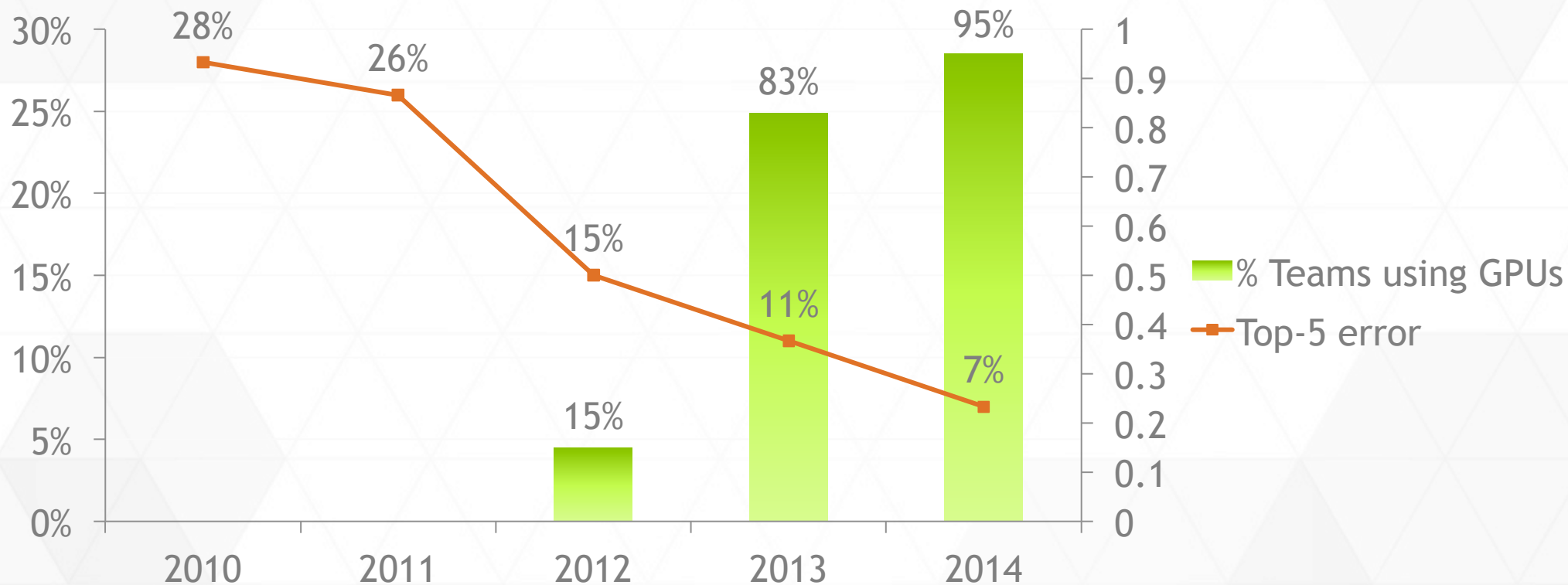
ImageNet

- ▶ Alex Krizhevsky et al, 2012
- ▶ 1.2M training images, 1000 classes
- ▶ Scored 15.3% Top-5 error rate with 26.2% for the second-best entry for classification task
- ▶ CNNs trained with **GPUs**



NATURAL IMAGE CLASSIFICATION

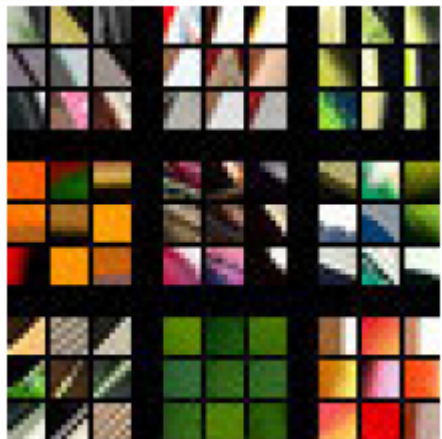
ImageNet: results for 2010-2014



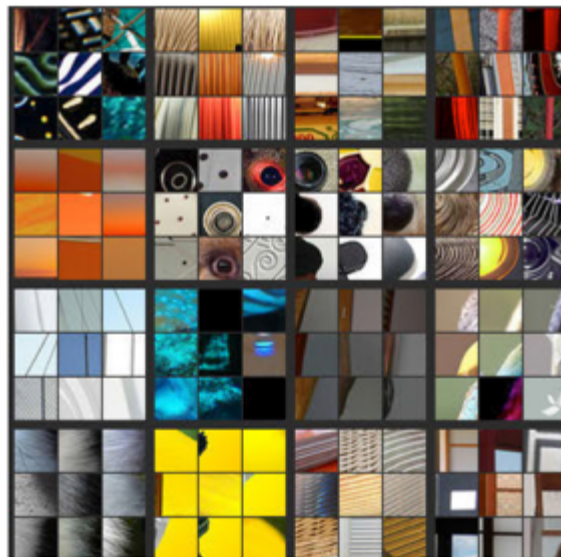
MODEL VISUALIZATION

- ▶ Matthew D. Zeiler, Rob Fergus

Layer 1



Layer 2



Layer 5



- ▶ Critique by Christian Szegedy et al

Visualizing and Understanding Convolutional Networks, <http://arxiv.org/abs/1311.2901>

Intriguing properties of neural networks, <http://arxiv.org/abs/1312.6199>

TRANSFER LEARNING

Dogs vs. Cats

- ▶ Dogs vs. Cats, 2014
- ▶ Train model on one dataset - ImageNet
- ▶ Re-train the last layer only on a new dataset - Dogs and Cats

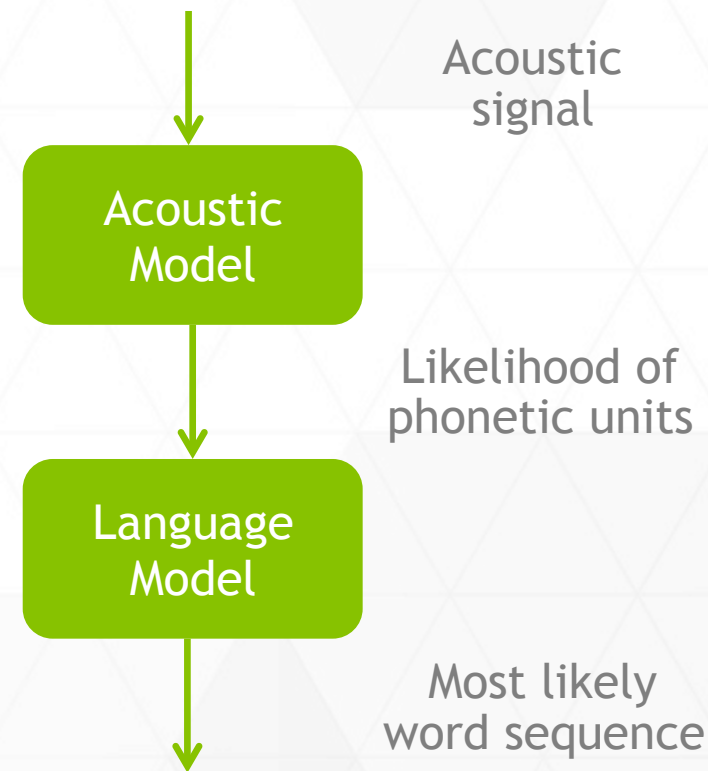


Rank	Team	Error rate	Model
1	Pierre Sermanet	1.1%	CNNs, model transferred from ImageNet
	...		
5	Maxim Milakov	1.9%	CNN, model trained on Dogs vs. Cat dataset only

SPEECH RECOGNITION

Acoustic model

- ▶ Acoustic model is DNN
 - ▶ Usually fully-connected layers
 - ▶ Some try using convolutional layers with spectrogram used as input
 - ▶ Both fit GPU perfectly
- ▶ Language model is weighted Finite State Transducer (wFST)
 - ▶ Beam search runs fast on GPU





*It is all about supercomputing,
right?*

GPU

Tesla K40 and Tegra K1

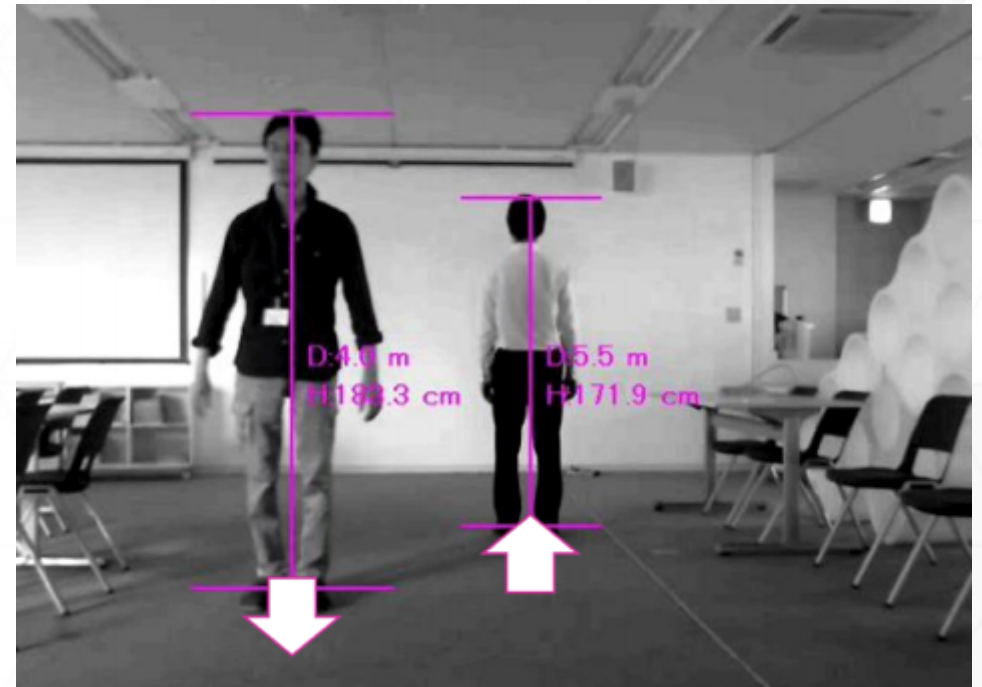


	NVIDIA Tesla K40	NVIDIA Jetson TK1
CUDA cores	2880	192
Peak performance, SP	4.29 Tflops	326 Gflops
Peak power consumption	235 Wt	~10 Wt, for the whole board
Deep Learning tasks	Training, Inference	Inference, Online Training
CUDA	Yes	Yes

PEDESTRIAN + GAZE DETECTION

Jetson TK1

- ▶ Ikuro Sato, Hideki Niihara, R&D Group, Denso IT Laboratory, Inc.
- ▶ Real-time pedestrian detection with depth, height, and **body orientation** estimations
- ▶ http://www.youtube.com/watch?v=9Y7yzi_w8qo



How do we run DNNs on GPUs?

CUDNN

cuDNN (and cuBLAS)

- ▶ Library for DNN toolkit developer and researchers
- ▶ Contains building blocks for DNN toolkits
 - ▶ Convolutions, pooling, activation functions e t.c.
- ▶ Best performance, easiest to deploy, future proofing
- ▶ Jetson TK1 support coming soon!
- ▶ developer.nvidia.com/cuDNN
- ▶ cuBLAS (SGEMM for fully-connected layers) is part of CUDA toolkit, developer.nvidia.com/cuda-toolkit

CUDNN

Frameworks

- ▶ cuDNN is already integrated in major open-source frameworks
- ▶ Caffe - caffe.berkeleyvision.org
- ▶ Torch - torch.ch
- ▶ Theano - deeplearning.net/software/theano/index.html, already has GPU support, cuDNN support coming soon!

REFERENCES

- ▶ HPC by NVIDIA: www.nvidia.com/tesla
- ▶ Jetson TK1 Development Kit: www.nvidia.com/jetson-tk1
- ▶ Jetson Pro: www.nvidia.com/object/jetson-automotive-development-platform.html
- ▶ CUDA Zone: developer.nvidia.com/cuda-zone
- ▶ Parallel Forall blog: devblogs.nvidia.com/parallelforall
- ▶ Contact me: mmilakov@nvidia.com



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